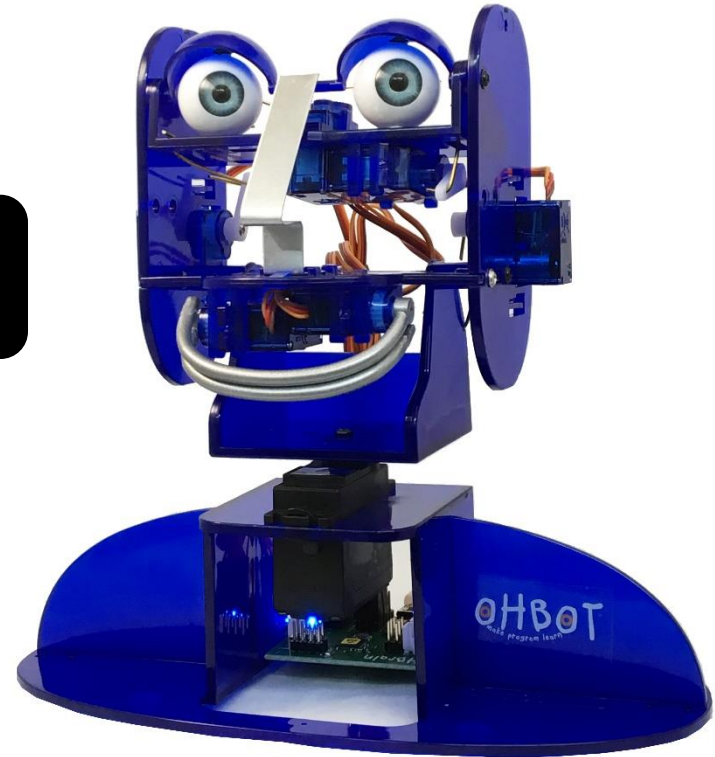


Lesson 1: Oh Puppet

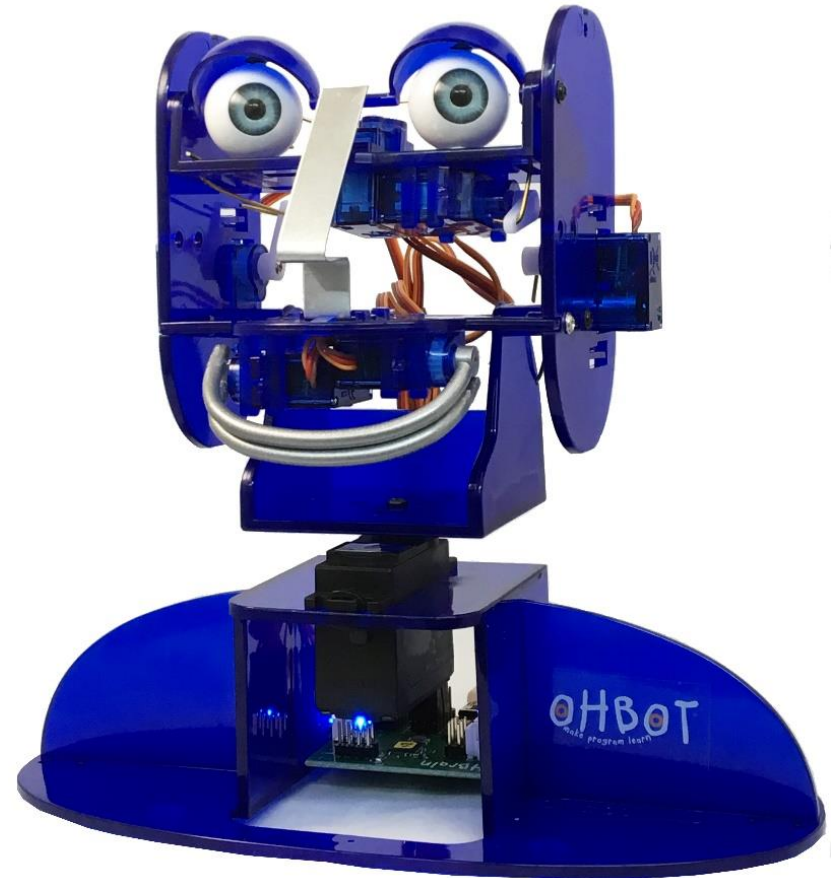
I can program a robot to sense the position of a mouse to set its position



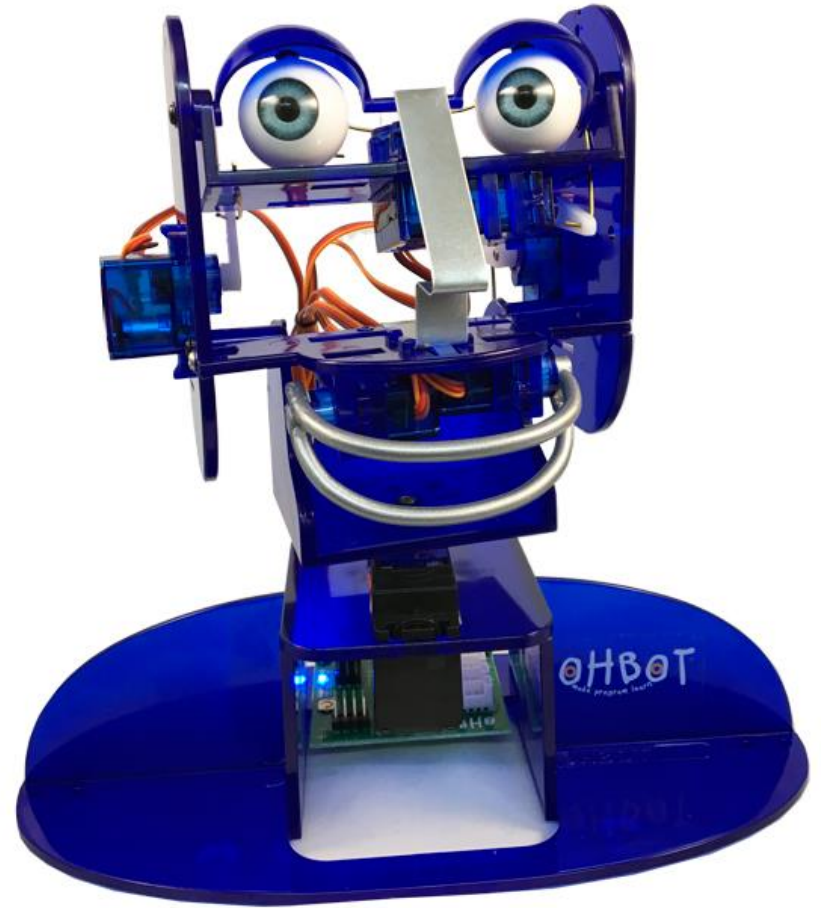
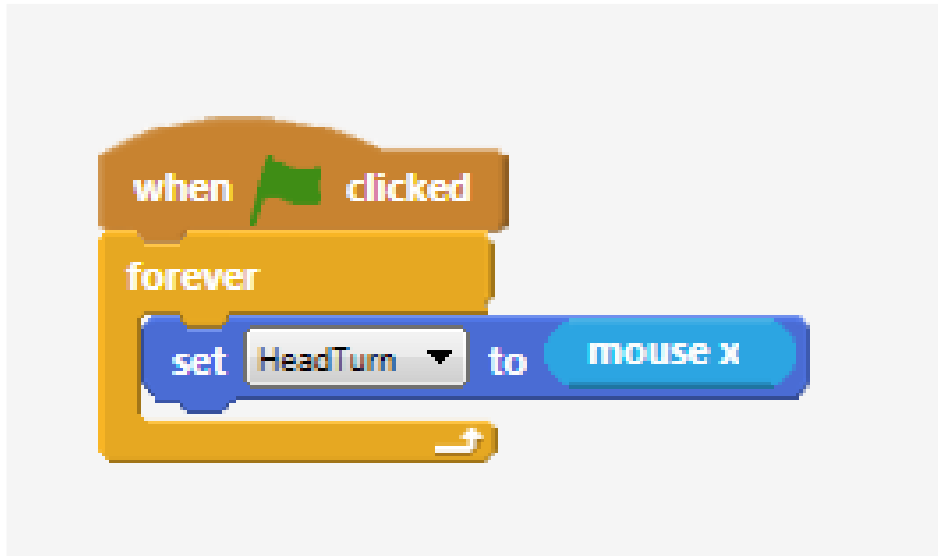
Demonstration

Together we will write a program which senses the position of the mouse and uses this to set the position of Ohbot's head turn motor.

File save as; "puppet head turn"



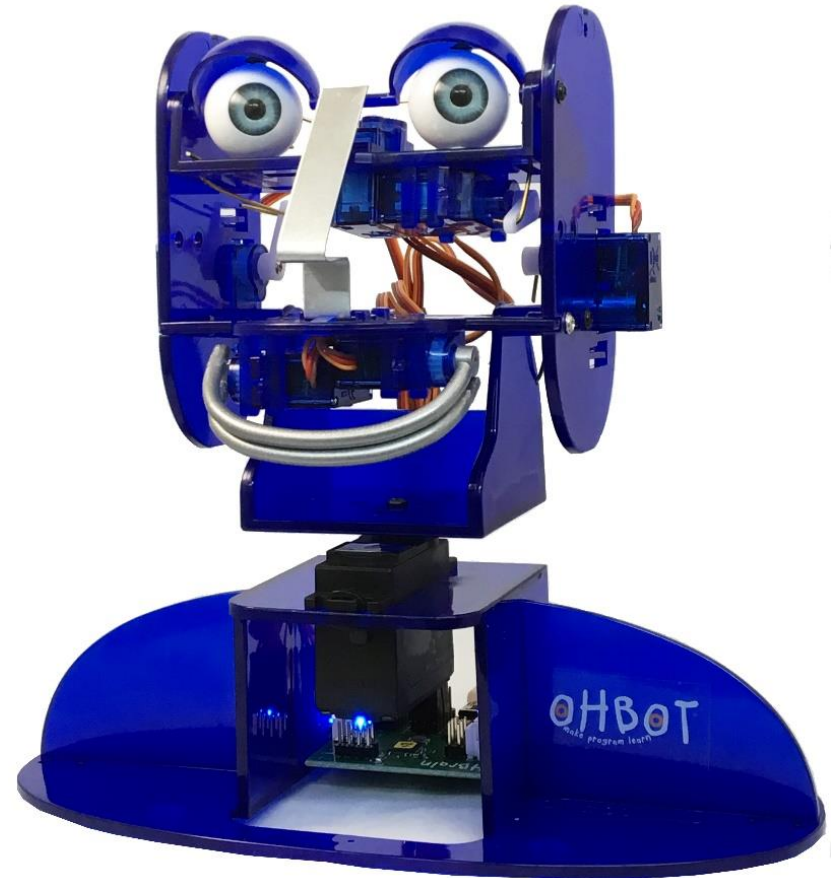
Head turn example



Activity 1

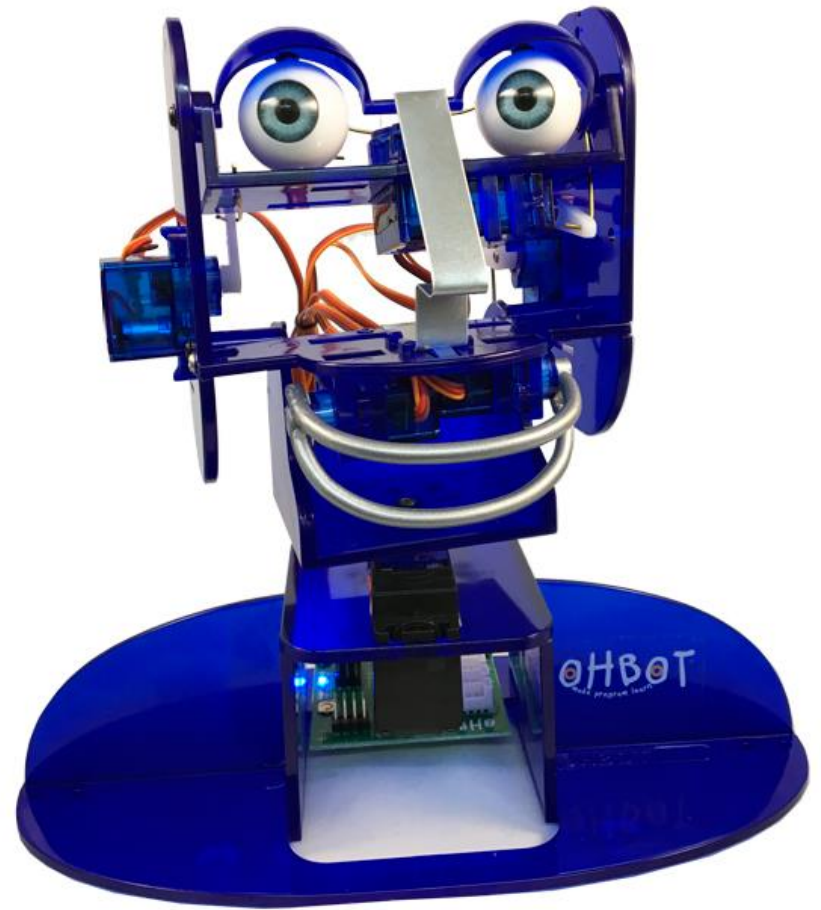
Can you write a program that allows the mouse to control Ohbot's head turn and head nod motors?

File save as "puppet"



Example: Activity 1

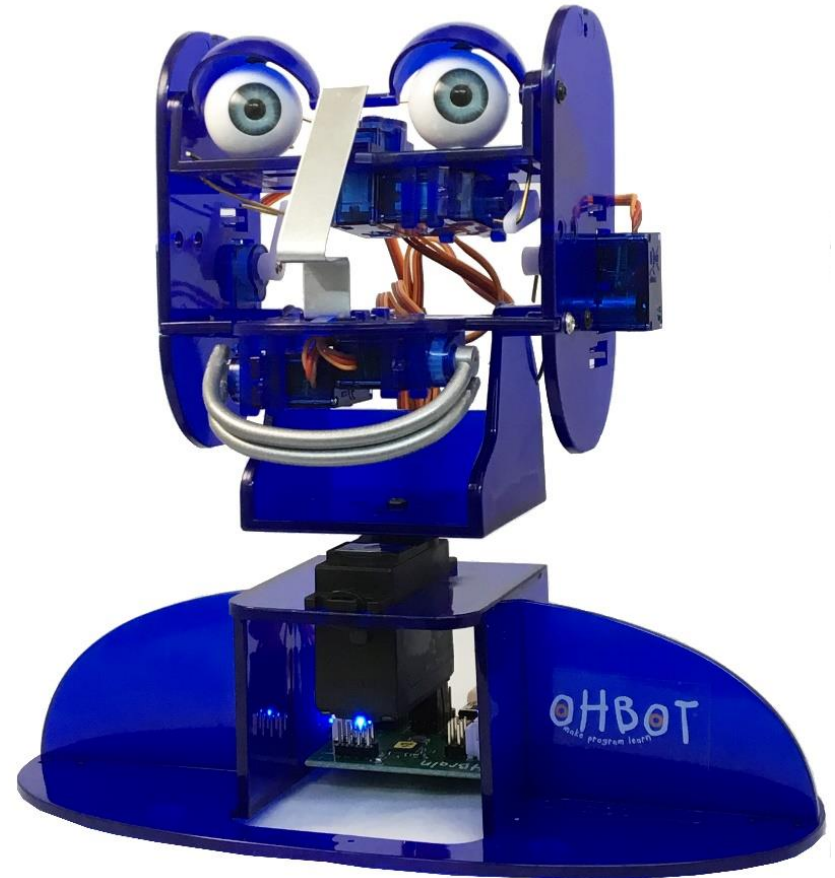
```
when clicked
  forever
    set HeadTurn to mouse x
    set HeadNod to mouse y
```



Activity 2

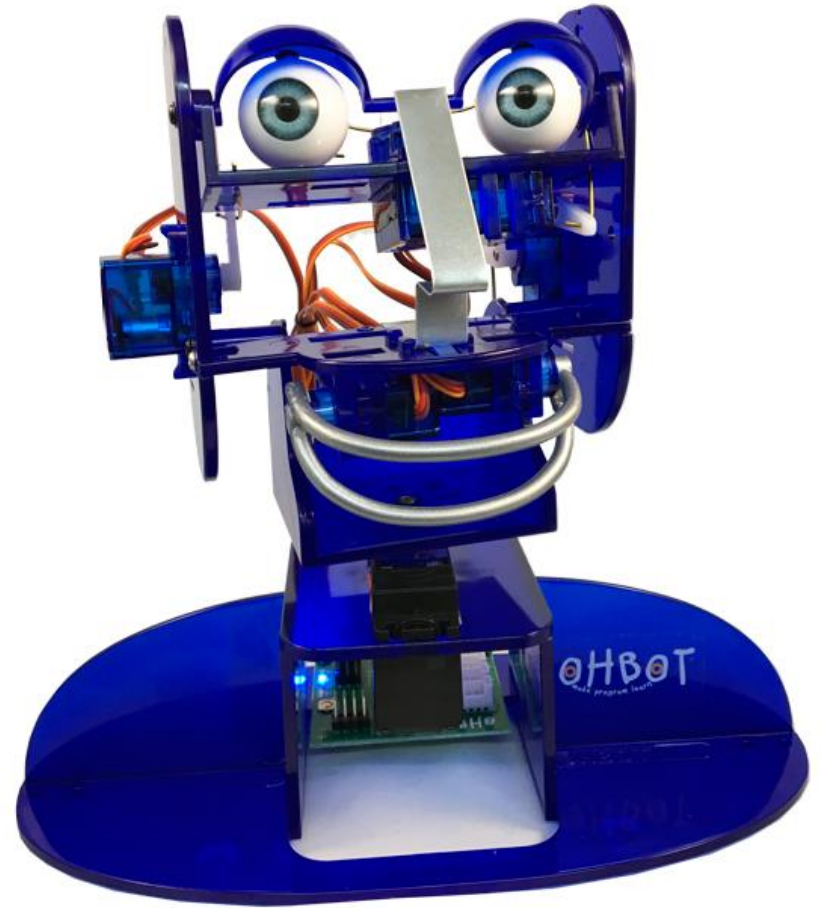
Can you add code to your program so that the mouse controls Ohbot's eye tilt and eye turn motors?

File save as "puppet head and eyes"



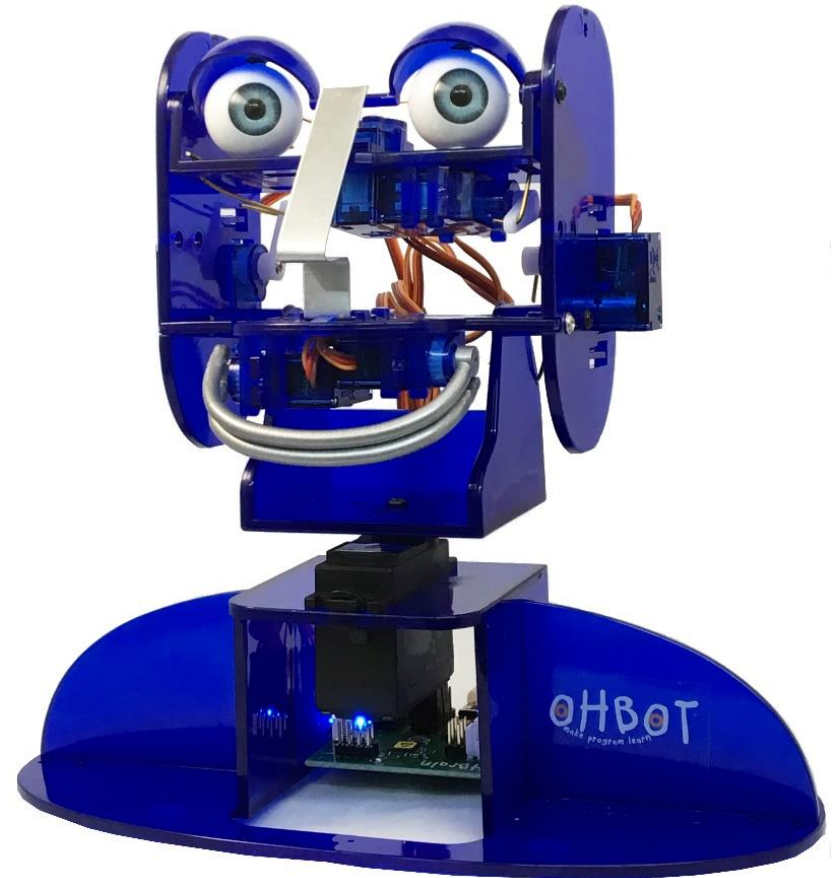
Head and eyes

```
when clicked
  forever
    set HeadTurn to mouse x
    set HeadNod to mouse y
    set EyeTurn to mouse x
    set EyeTilt to mouse y
```



Activity 3

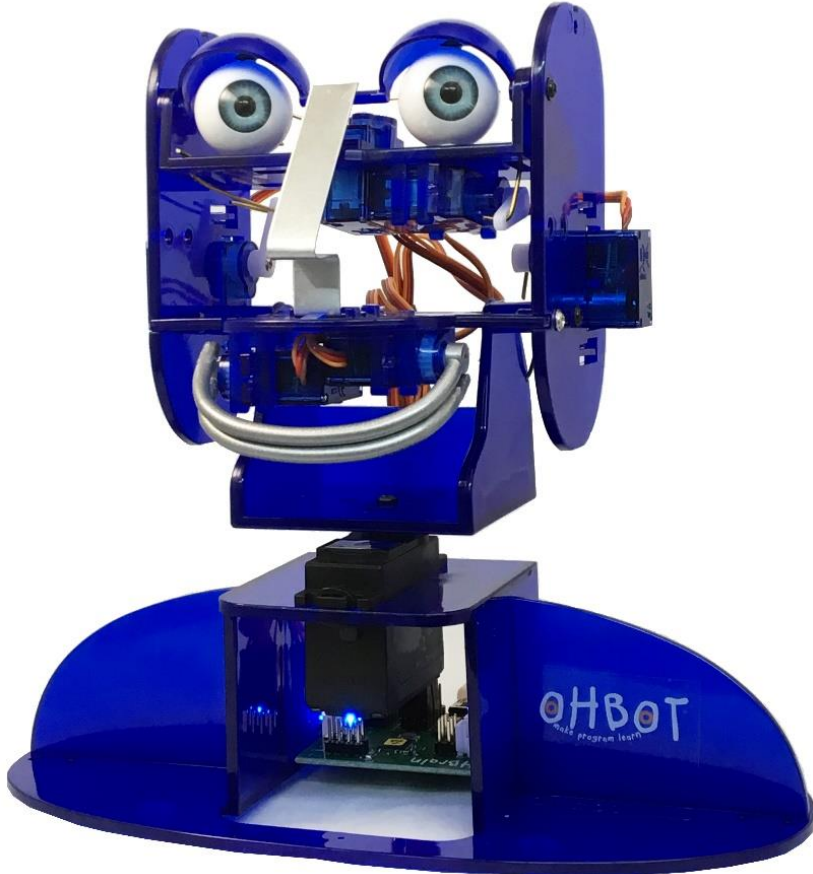
Can you experiment with using the mouse to control Ohbot's mouth motors.



Activity 3

```
when S key pressed  
say Greetings ladies and gentlemen! until done
```

```
when clicked  
forever  
  set TopLip to toplip  
  set BottomLip to bottomlip
```



Extension

Can you add code to your program to make Ohbot perform using speech and movement?

